Controlled Markovian dynamics of structured graphs

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ES Roberts, A Annibale, ACC Coolen (KCL) Controlled Markovian dynamics of graphs

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Background - tailored random graphs

- Generating tailored random graphs numerically
- 3 Constrained Markovian graph dynamics
- 4 Degree-constrained dynamics of nondirected graphs
- 5 Degree-constrained dynamics of directed graphs
- Summary

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Background - tailored random graphs

networks/graphs:

number of nodes: Nnodes (vertices): $i, j \in \{1, ..., N\}$

links (edges): $c_{ij} \in \{0, 1\}$ no self-links: $c_{ii} = 0$ for all igraph: $\mathbf{c} = \{c_{ij}\}$

nondirected: directed:

$$orall (i,j): c_{ij} = c_{ji} \ \exists (i,j): c_{ij}
eq c_{ji}$$





degrees: $k_i^{\text{in}}(\mathbf{c}) = \sum_j c_{ij}, \quad k_i^{\text{out}}(\mathbf{c}) = \sum_j c_{ji}$ $\mathbf{k}^{\text{in}}(\mathbf{c}) = (k_1^{\text{in}}(\mathbf{c}), \dots, k_N^{\text{in}}(\mathbf{c})), \quad \mathbf{k}^{\text{out}}(\mathbf{c}) = \dots$

Networks in cellular biology

 protein interaction networks: (nondirected)

nodes: proteins $i, j = 1 \dots N$ links: $c_{ij} = c_{ji} = 1$ if *i* can bind to *j* $c_{ij} = c_{ji} = 0$ otherwise $N \sim 10^4$, about 7 links/node

 gene regulation networks: (directed)

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Quantify graph topology beyond degrees

joint degree statistics of connected nodes

$$\mathcal{W}(k,k'|\mathbf{c}) = rac{1}{N\langle k
angle}\sum_{ij} c_{ij}\delta_{k,k_i(\mathbf{c})}\delta_{k',k_j(\mathbf{c})}$$



W(*k*|**c**) = *p*(*k*|**c**)*k*/⟨*k*⟩ so focus on:

$$\Pi(k,k'|\mathbf{c}) = rac{W(k,k'|\mathbf{c})}{W(k|\mathbf{c})W(k'|\mathbf{c})}$$

 $\Pi(k, k' | \mathbf{c}) \neq 1$: structural information in degree correlat



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• $W(k|\mathbf{c}) = p(k|\mathbf{c})k/\langle k \rangle$ $\Pi(k,k'|\mathbf{c}) = \frac{W(k,k'|\mathbf{c})}{W(k|\mathbf{c})W(k'|\mathbf{c})}$ so focus on:

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for directed graphs:

joint in-out degree statistics of connected nodes

 $k_i \ \rightarrow \ \vec{k}_i = (k_i^{\rm in},k_i^{\rm out})$

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 $W(\vec{k}'|\mathbf{c}) \equiv \sum_{\vec{k}} W(\vec{k}, \vec{k}') = p(\vec{k}'|\mathbf{c})k^{\text{out}}/\langle k \rangle$

so focus on

$$\Pi(\vec{k},\vec{k}'|\mathbf{c}) = \frac{W(\vec{k},\vec{k}'|\mathbf{c})}{W_1(\vec{k}|\mathbf{c})W_2(\vec{k}'|\mathbf{c})}$$

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Graph classification via increasingly detailed measurements

we are led to study:

Tailored random graph ensembles



maximum entropy random graph ensembles, with prescribed values for $\langle k \rangle$, p(k), $\Pi(k, k')$,...

- proxies for real networks in stat mech process modelling
- complexity: how many networks exist with same features as c?
- hypothesis testing: graphs with controlled features as null models
- quantifying network dissimilarity

analytically in leading order in N

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effective nr of graphs in ensemble $p(\mathbf{c})$, complexity of tailored random graphs

$$\mathcal{N} = e^{N\langle k \rangle S}, \qquad S = -\frac{1}{N\langle k \rangle} \sum_{\mathbf{c}} p(\mathbf{c}) \log p(\mathbf{c})$$

nondirected graphs:

$$p(\mathbf{c}) = \frac{\prod_{i} \delta_{k_{i},k_{i}(\mathbf{c})}}{Z} \prod_{i < j} \left[\frac{\langle k \rangle}{N} \frac{W(k_{i},k_{j})}{p(k_{i})p(k_{j})} \delta_{c_{ij},1} + \left(1 - \frac{\langle k \rangle}{N} \frac{W(k_{i},k_{j})}{p(k_{i})p(k_{j})} \right) \delta_{c_{ij},0} \right]$$

- write
$$\delta_{k_i,k_i(\mathbf{c})} = (2\pi)^{-1} \int_0^{2\pi} \mathrm{d}\omega_i \, \mathrm{e}^{\mathrm{i}\omega_i [k_i - k_i(\mathbf{c})]}$$

- factorisation over bonds, sum over graphs
- write as path integral over $P(k,\omega) = N^{-1} \sum_i \delta_{k,k_i} \delta(\omega \omega_i)$
- integration via steepest descent
- solve saddle-point equation analytically

$$S = \frac{1}{2} \left[1 + \log(\frac{N}{\langle k \rangle})\right] - \left\{\frac{1}{\langle k \rangle} \sum_{k} p(k) \log[\frac{1}{\pi(k)}] + \frac{1}{2} \sum_{k,k'} W(k,k') \log\left[\frac{W(k,k')}{W(k)W(k')}\right]\right\}$$

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with $\vec{k}_{i}(\mathbf{c}) = (k_{i}^{\mathrm{in}}(\mathbf{c}), k_{i}^{\mathrm{out}}(\mathbf{c}))$

similar methods ... final result:

$$S = 1 + \log(\frac{N}{\langle k \rangle}) - \left\{ \frac{1}{\langle k \rangle} \sum_{\vec{k}} p(\vec{k}) \log[\frac{1}{\pi(k^{\text{in}})\pi(k^{\text{out}})}] + \sum_{\vec{k},\vec{k}'} W(\vec{k},\vec{k}') \log\left[\frac{W(\vec{k},\vec{k}')}{W(\vec{k})W(\vec{k}')}\right] \right\}$$

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Information in degree correlations?

plot $\Pi(k, k') = W(k, k')/W(k)W(k')$ for protein interaction networks: a problem ...





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structural dissimilarity of graphs c_A and c_B , based on **Information-theoretic distance between associated ensembles**

$$D_{AB} = \frac{1}{2N} \sum_{\mathbf{c} \in G} \left\{ p(\mathbf{c}|p_A, W_A) \log \left[\frac{p(\mathbf{c}|p_A, W_A)}{p(\mathbf{c}|p_B, W_B)} \right] + p(\mathbf{c}|p_B, W_B) \log \left[\frac{p(\mathbf{c}|p_B, W_B)}{p(\mathbf{c}|p_A, W_A)} \right] \right\}$$

same methods as in calculating Shannon entropy:

$$D_{AB} = \frac{1}{2} \sum_{k} p_{A}(k) \log \left[\frac{p_{A}(k)}{p_{B}(k)} \right] + \frac{1}{2} \sum_{k} p_{B}(k) \log \left[\frac{p_{B}(k)}{p_{A}(k)} \right]$$
$$+ \frac{1}{4 \langle k \rangle_{A}} \sum_{kk'} p_{A}(k) p_{A}(k') kk' \Pi_{A}(k,k') \log \left[\frac{\Pi_{A}(k,k')}{\Pi_{B}(k,k')} \right]$$
$$+ \frac{1}{4 \langle k \rangle_{B}} \sum_{kk'} p_{B}(k) p_{B}(k') kk' \Pi_{B}(k,k') \log \left[\frac{\Pi_{B}(k,k')}{\Pi_{A}(k,k')} \right]$$
$$+ \frac{1}{2} \sum_{k} p_{A}(k) k \log \rho_{AB}(k) + \frac{1}{2} \sum_{k} p_{B}(k) k \log \rho_{BA}(k)$$

with

$$\Pi(k,k') = W(k,k)/W(k)W(k'), \qquad \rho_{AB}(k) = \sum \Pi_B(k,k')W_A(k')\rho_{AB}^{-1}(k')$$

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clustering of protein interaction networks with information-theoretic distance measure



- PINs of same species and measured via same experimental method are statistically similar (in spite of limited overlap)
- PINs measured via same method cluster together, revealing bias introduced by experimental method that overrules species information

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finally: let us

generate tailored random graphs

from the above families numerically ...

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Generating tailored random graphs numerically

 $G[\mathbf{k}]$: all nondirected graphs \mathbf{c} with degrees \mathbf{k}

how to generate

- random $\mathbf{c} \in G[\mathbf{k}]$, with uniform probability
- random c ∈ G[k], with specified probability p(c) (e.g. tailored graphs)



available approaches

- matching algorithm (Bender & Canfield, 1978)
 builds one random graph c with specified degrees k
 (assign k_i 'stubs' to each node i, then randomly connect pairs of 'stubs')
- edge switching algorithm (Seidel, 1976; Taylor, 1981) ergodic Markov process in *G*[k]
 c → c' → c'' → ...
- sampling all graphs in G[k]: in principle easy
- main problem: sampling with correct probabilities
- matching and edge switching: both biased (yet widely used ...

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Matching algorithm

- stochastic growth dynamics
- start with graph without any links
- pick at random two nodes whose in- and out degrees have not yet reached required values, and connect these if possible (Bender & Canfield, 1978)

bond creation as elementary moves: $c_{ij} = 0 \rightarrow c_{ij} = 1$ if $k_i^{\text{in}}(\mathbf{c}) < k_i^{\text{in}}$ and $k_j^{\text{out}}(\mathbf{c}) < k_j^{\text{out}}$

origin of sampling bias:

- process can terminate before $k_i(\mathbf{c}) = k_i$ for all *i* (e.g. if remaining 'stubs' require self-loops)
- requires 'backtracking' which creates correlations between graph realisations



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- start with graph without any links
- pick at random two nodes whose in- and out degrees have not yet reached required values, and connect these if possible (Bender & Canfield, 1978)

bond creation as elementary moves: $c_{ij} = 0 \rightarrow c_{ij} = 1$ if $k_i^{\text{in}}(\mathbf{c}) < k_i^{\text{in}}$ and $k_j^{\text{out}}(\mathbf{c}) < k_j^{\text{out}}$

origin of sampling bias:

- process can terminate before $k_i(\mathbf{c}) = k_i$ for all *i* (e.g. if remaining 'stubs' require self-loops)
- requires 'backtracking' which creates correlations between graph realisations



dangerous for scale-free graphs ...

Edge switching

- construct arbitrary graph with degrees k
- shuffle links repeatedly via randomly drawn 'edge swaps' (Seidel, 1976)

edge swaps as elementary moves:

preserve the degrees of all nodes
 are ergodic on G[k] (Taylor, 1981)

origin of sampling bias: nr of possible moves depends on state **c**!

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need to study graph dynamics more systematically ...

• constraints: $G[*] \subseteq G$: all $\mathbf{c} \in G$ that satisfy constraints *

 stochastic graph dynamics as a Markov chain, transition probabilities W(c|c')

$$orall \mathbf{c} \in G[\star]: \qquad p_{t+1}(\mathbf{c}) = \sum_{\mathbf{c}' \in G[\star]} W(\mathbf{c}|\mathbf{c}') p_t(\mathbf{c}')$$

allowed moves (exclude identity):

Φ: set of allowed moves $F : G_F[*] → G[*]$ $G_F[*]$: those **c** ∈ G[*] on which *F* can act

all moves are auto-invertible: $(\forall F \in \Phi) : F^2 = \mathbb{1}$ Φ is ergodic on G[*]

graph mobility n(c):

$$n(\mathbf{c}) = \sum_{F \in \Phi} I_F(\mathbf{c}), \qquad I_F(\mathbf{c}) = \begin{cases} 1 & \text{if } \mathbf{c} \in G_F[\star] \\ 0 & \text{if } \mathbf{c} \notin G_F[\star] \end{cases}$$

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MCMC objective

construct transition probs $W(\mathbf{c}|\mathbf{c}')$, based on moves $F \in \Phi$, such that process converges to $p_{\infty}(\mathbf{c}) = Z^{-1}e^{-H(\mathbf{c})}$ on $G[\star]$

structure:

$$W(\mathbf{c}|\mathbf{c}') = \sum_{F \in \Phi} q(F|\mathbf{c}') \Big[\delta_{\mathbf{c},F\mathbf{c}'} A(F\mathbf{c}'|\mathbf{c}') + \delta_{\mathbf{c},\mathbf{c}'} [1 - A(F\mathbf{c}'|\mathbf{c}')] \Big]$$

q(F|**c**) : move proposal probability A(**c**|**c**') : move acceptance probability

detailed balance condition:

 $(\forall F \in \Phi)(\forall \mathbf{c} \in G[\star]): \qquad q(F|\mathbf{c})A(F\mathbf{c}|\mathbf{c})e^{-H(\mathbf{c})} = q(F|F\mathbf{c})A(\mathbf{c}|F\mathbf{c})e^{-H(F\mathbf{c})}$

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corollary:

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ES Roberts, A Annibale, ACC Coolen (KCL) Controlled Markovian dynamics of graphs

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Master equation representation of the process

• soln of Markov chain:
$$p_n(\mathbf{c})$$
, $n = 0, 1, 2, ...$

continuous time process, $p_t(\mathbf{c}), t \in [0, \infty)$ via *random durations* of MC steps

 $\pi_m(t) = (t/\tau)^m \mathrm{e}^{-t/\tau}/m!$

prob that at time t precisely m MC steps have been made

$$au rac{\mathrm{d}}{\mathrm{d}t} p_t(\mathbf{c}) = \sum_{\mathbf{c}' \in G[\star]} W(\mathbf{c}|\mathbf{c}') p_t(\mathbf{c}') - p_t(\mathbf{c})$$

 work out details, using Δ_FU(c) = U(Fc) - U(c)

$$\tau \frac{\mathrm{d}}{\mathrm{d}t} p_t(\mathbf{c}) = \sum_{F \in \Phi} I_F(\mathbf{c}) \left\{ \frac{w_F^+(\mathbf{c})}{n(F\mathbf{c})} p_t(F\mathbf{c}) - \frac{w_F^-(\mathbf{c})}{n(\mathbf{c})} p_t(\mathbf{c}) \right\}$$
$$w_F^{\pm}(\mathbf{c}) = \frac{1}{2} \pm \frac{1}{2} \tanh \left[\frac{1}{2} \Delta_F [H(\mathbf{c}) + \log n(\mathbf{c})] \right]$$

Convergence:

$$let \quad \hat{p}(\mathbf{c}) = Z^{-1} e^{-H(\mathbf{c})}, \qquad F(t) = \sum_{\mathbf{c} \in G[\star]} p_t(\mathbf{c}) \log[p_t(\mathbf{c})/\hat{p}(\mathbf{c})]$$

- F(t) is Lyapunov function $\forall t \ge 0$: $F(t) \ge 0$, $\frac{d}{dt}F(t) \le 0$
- Proof (standard):

use detailed balance

$$\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t}F(t) &= -\frac{1}{2\tau} \sum_{\mathbf{c},\mathbf{c}' \in G[\star]} W(\mathbf{c}|\mathbf{c}') \mathrm{e}^{-H(\mathbf{c}')} \Big[[H(\mathbf{c}) + \log p_t(\mathbf{c})] - [H(\mathbf{c}') + \log p_t(\mathbf{c}')] \Big] \\ &\times \Big[\mathrm{e}^{H(\mathbf{c}) + \log p_t(\mathbf{c})} - \mathrm{e}^{H(\mathbf{c}') + \log p_t(\mathbf{c}')} \Big] \leq 0 \end{aligned}$$

 $(e^x - e^y)(x - y) \ge 0$, equality only if x = y

• stationarity:
$$\frac{d}{dt}F(t) = 0$$
,
write $p(\mathbf{c}) = \chi(\mathbf{c})e^{-H(\mathbf{c})}$,
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 $(\forall \mathbf{c}, \mathbf{c}' \in G[\star]): \quad W(\mathbf{c}|\mathbf{c}') = 0 \text{ or } \chi(\mathbf{c}) = \chi(\mathbf{c}')$
 $ergodic \Rightarrow \chi(\mathbf{c}) = const \Rightarrow p(\mathbf{c}) = Z^{-1}e^{-H(\mathbf{c})} = \hat{p}(\mathbf{c})$

Degree-constrained dynamics of nondirected graphs

constraints: imposed degrees, so graph set is G[k]

ergodic set Φ of admissible moves: edge swaps $F: G_F[\mathbf{k}] \rightarrow G[\mathbf{k}]$

 $Q = \{(i, j, k, \ell) \in \{1, \dots, N\}^4 | i < j < k < \ell\}, \text{ ordered node quadruplets}$

possible edge swaps to act on (i, j, k, ℓ) :



 $F_{ijk\ell;lpha}(\mathbf{c})_{qr} = c_{qr} \qquad ext{for } (q,r) \notin S_{ijk\ell;lpha}$

 $S_{ijk\ell;1} = \{(i,j), (k,\ell), (i,\ell), (j,k)\}, \quad S_{ijk\ell;2} = \{(i,j), (k,\ell), (i,k), (j,\ell)\}$ $S_{ijk\ell;3} = \{(i,k), (j,\ell), (i,\ell), (j,k)\}$

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• group into pairs (I,IV), (II,V), and (III,VI) auto-invertible swaps: $F_{ijk\ell;\alpha}$, with $i < j < k < \ell$ and $\alpha \in \{1, 2, 3\}$

$$\begin{aligned} F_{ijk\ell;\alpha}(\mathbf{c}) &= 1: \\ F_{ijk\ell;\alpha}(\mathbf{c})_{qr} &= 1 - c_{qr} \quad \text{for } (q,r) \in \mathcal{S}_{ijk\ell;\alpha} \\ F_{ijk\ell;\alpha}(\mathbf{c})_{qr} &= c_{qr} \quad \text{for } (q,r) \notin \mathcal{S}_{ijk\ell;\alpha} \end{aligned}$$

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$$n(\mathbf{c}) = \sum_{i < j < k < \ell}^{N} \sum_{\alpha=1}^{3} I_{ijk\ell;\alpha}(\mathbf{c}) \dots$$

$$\begin{split} I_{ijk\ell;1}(\mathbf{c}) &= c_{ij}c_{k\ell}(1-c_{i\ell})(1-c_{jk}) + (1-c_{ij})(1-c_{k\ell})c_{i\ell}c_{jk}c_{jk}\\ I_{ijk\ell;2}(\mathbf{c}) &= c_{ij}c_{k\ell}(1-c_{ik})(1-c_{j\ell}) + (1-c_{ij})(1-c_{k\ell})c_{ik}c_{j\ell}\\ I_{ijk\ell;3}(\mathbf{c}) &= c_{ik}c_{j\ell}(1-c_{i\ell})(1-c_{jk}) + (1-c_{ik})(1-c_{j\ell})c_{i\ell}c_{jk}c$$

combinatorial problem easily solved:

$$n(\mathbf{c}) = \underbrace{\frac{1}{4}N^2 \langle k \rangle^2 + \frac{1}{4}N \langle k \rangle - \frac{1}{2}N \langle k^2 \rangle}_{invariant} + \underbrace{\frac{1}{4}\mathrm{Tr}(\mathbf{c}^4) + \frac{1}{2}\mathrm{Tr}(\mathbf{c}^3) - \frac{1}{2}\sum_{ij}k_i c_{ij}k_j}_{invariant}$$

state dependent

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- state-dependent part can be ignored if $\langle k^2 \rangle k_{max} / \langle k \rangle^2 \ll N$ (in which case naive edge swapping is harmless)
- computational feasibility: calculate change $\Delta_{ijk\ell;\alpha}n(\mathbf{c})$ for each executed move $F_{ijk\ell;\alpha}$

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many possible moves

only one move ...



executed moves

N = 100

naive versus correct acceptance probabilities

predictions:

 $p(\mathbf{c}) = constant:$ $\overline{n(\mathbf{c})}/N^2 \approx 0.0195$

 $p(\mathbf{c}) = n(\mathbf{c})/Z$: $\overline{n(\mathbf{c})}/N^2 \approx 0.0242$

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Example





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Degree-constrained dynamics of directed graphs

constraints: imposed in-out degrees, so graph set is G[kⁱⁿ, k^{out}]

set Φ of admissible moves: directed edge swaps $F: G_F[\mathbf{k}^{in}, \mathbf{k}^{out}] \to G[\mathbf{k}^{in}, \mathbf{k}^{out}]$



• auto-invertible edge-swaps: Let $\Lambda = \{(i, j) \in N^2 | c_{ij} = 1\}$

 $I_{(i_x,j_x),(i_y,j_y);\Box} = \begin{cases} 1 & \text{if } (i_x,j_x), (i_y,j_y) \in \Lambda \text{ and } (i_x,j_y), (i_y,j_x) \notin \Lambda \\ 0 & \text{otherwise} \end{cases}$

 $\begin{array}{ll} \text{If } l_{(i_x,j_x),(i_y,j_y);\Box} = 1 : \\ & F_{(i_x,j_x),(i_y,j_y);\Box}(\mathbf{c})_{ij} = 1 - c_{ij} & \text{if } i \in \{i_x,i_y\} \text{ and } j \in \{j_x,j_y\} \\ & F_{(i_x,j_x),(i_y,j_y);\Box}(\mathbf{c})_{ij} = c_{ij} & \text{otherwise} \end{array}$

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difference with nondirected graphs:

edge swaps *no longer ergodic* (Rao, 1996) (unless self-interactions are allowed)

further move type required to restore ergodicity: 3-loop reversal



$$I_{(i_x,j_x),(i_y,j_y);\triangle} = \begin{cases} 1 \\ 0 \end{cases}$$

if
$$(i_x, j_x), (i_y, j_y), (j_y, i_x) \in \Lambda$$
 and $x_j = y_i$
and $(j_x, i_x), (j_y, i_y), (i_x, j_y) \notin \Lambda$
otherwise

$$\begin{array}{rcl} F_{(i_x,j_x),(i_y,j_y);\triangle}(\mathbf{c})_{ij} &=& 1-c_{ij} \quad \textit{for } (i,j) \in \mathcal{S}_{i_x,j_x,j_y} \\ F_{(i_x,j_x),(i_y,j_y);\triangle}(\mathbf{c})_{ij} &=& c_{ij} \quad \quad \textit{for } (i,j) \notin \mathcal{S}_{i_x,j_x,j_y} \end{array}$$

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combinatorial problem easily solved:

1

$$n_{\Box}(\mathbf{c}) = \underbrace{\frac{1}{2}N^{2}\langle k \rangle^{2} - \sum_{j}k_{j}^{\mathrm{in}}k_{j}^{\mathrm{out}} + \frac{1}{2}\mathrm{Tr}(\mathbf{c}^{2}) + \frac{1}{2}\mathrm{Tr}(\mathbf{c}^{\dagger}\mathbf{c}\mathbf{c}^{\dagger}\mathbf{c}) + \mathrm{Tr}(\mathbf{c}^{2}\mathbf{c}^{\dagger}) - \sum_{ij}k_{i}^{\mathrm{in}}c_{ij}k_{j}^{\mathrm{out}}}_{invariant}}_{state \ dependent}$$

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ES Roberts, A Annibale, ACC Coolen (KCL) Controlled Markovian dynamics of graphs

to implement the Markov chain, need to calculate graph mobility **analytically**:

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Example



predicted values versus equilibrated dynamics for $\langle n(\mathbf{c}) \rangle / N^2$:

	prediction for $p(\mathbf{c}) = const$	dynamics with $A(\mathbf{c} \mathbf{c}') = 1$	dynamics with $A(\mathbf{c} \mathbf{c}') = [1 + \frac{n(\mathbf{c})}{n(\mathbf{c}')}]^{-1}$
<i>N</i> = 17:	27.87	33.59	27.87
N = 27:	47.92	58.32	47.95

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Summary

- standard 'matching' end 'edge swapping' algorithms, for generating graphs c with prescribed degrees, are both biased
- need exact method for generating random graphs c with prescribed degrees and prescribed sampling probabilities p(c)
- exact degree constrained Markovian graph dynamics can be defined, guaranteed to evolve to any prescribed measure p(c)
- process requires nontrivial state acceptance probabilities, that involve the mobilities *n*(**c**) of states
- nondirected graph: edge swaps only directed graphs: edge swaps and 3-cycle reversals
- mobilities can be calculated exactly
- theory worked out, implemented and tested for nondirected and directed graphs

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A (10) A (10) A (10)

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Development of theory for tailored graph ensembles characterised by statistics of **loops** ...

(in addition to degrees and degree correlations)

- calculate Shannon entropies
- dynamics (constrained by degrees and loops)
- graph ensembles defined by eigenvalue spectrum
- loops versus closed paths (see talk by Clara Gracio)



protein interaction networks

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protein interaction networks

2011/9/2011

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 Conrad Pérez-Vicente
 Clara Gracio
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Luis Fernandes Franca Fraternali Jens Kleinjung Thomas Schlitt

grants:

ΒΡΖΚ



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