## Controlled Markovian dynamics of structured graphs

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## Outline

(1) Background-tailored random graphs

Generating tailored random graphs numerically

Constrained Markovian graph dynamics

Degree-constrained dynamics of nondirected graphs

Degree-constrained dynamics of directed graphs

Summary

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## Background - tailored random graphs

## networks/graphs:

number of nodes: $N$ nodes (vertices): $\quad i, j \in\{1, \ldots, N\}$
links (edges):
$c_{i j} \in\{0,1\}$
no self-links:
$c_{i i}=0$ for all $i$
$\mathbf{c}=\left\{c_{i j}\right\}$
nondirected: $\quad \forall(i, j): c_{i j}=c_{j i}$
directed: $\quad \exists(i, j): c_{i j} \neq c_{j i}$

degrees: $\quad k_{i}^{\text {in }}(\mathbf{c})=\sum_{j} c_{i j}, \quad k_{i}^{\text {out }}(\mathbf{c})=\sum_{j} c_{j i}$

$$
\mathbf{k}^{\mathrm{in}}(\mathbf{c})=\left(k_{1}^{\mathrm{in}}(\mathbf{c}), \ldots, k_{N}^{\text {in }}(\mathbf{c})\right), \mathbf{k}^{\mathrm{out}}(\mathbf{c})=\ldots
$$

## Networks in cellular biology

- protein interaction networks: (nondirected)
nodes: proteins $i, j=1 \ldots N$
links: $c_{i j}=c_{j i}=1$ if $i$ can bind to $j$
$c_{i j}=c_{j i}=0 \quad$ otherwise
$N \sim 10^{4}$, about 7 links/node
- gene regulation networks:

(directed)

$N \sim 10^{4}$, about 5 links/node



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- gene regulation networks: (directed)
nodes: proteins $i, j=1 \ldots N$
links: $c_{i j}=c_{j i}=1$ if $j$ is transcription factor of $i$

$$
c_{i j}=c_{j i}=0 \quad \text { otherwise }
$$

$N \sim 10^{4}$, about 5 links/node


## Quantify graph topology beyond degrees

joint degree statistics of connected nodes

$$
W\left(k, k^{\prime} \mid \mathbf{c}\right)=\frac{1}{N\langle k\rangle} \sum_{i j} c_{i j} \delta_{k, k_{i}(\mathbf{c})} \delta_{k^{\prime}, k_{j}(\mathbf{c})}
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$$



$$
k_{i}=k ?
$$

$$
k_{j}=k^{\prime} ?
$$

- $W(k \mid \mathbf{c})=p(k \mid \mathbf{c}) k /\langle k\rangle$
so focus on:

$$
\Pi\left(k, k^{\prime} \mid \mathbf{c}\right)=\frac{W\left(k, k^{\prime} \mid \mathbf{c}\right)}{W(k \mid \mathbf{c}) W\left(k^{\prime} \mid \mathbf{c}\right)}
$$

$\Pi\left(k, k^{\prime} \mid \mathbf{c}\right) \neq 1$ :
structural information in degree correlations


H sapiens PIN $N=9306$ $\langle k\rangle=7.53$

## for directed graphs:

joint in-out degree statistics
of connected nodes
$k_{i} \rightarrow \vec{k}_{i}=\left(k_{i}^{\text {in }}, k_{i}^{\text {out }}\right)$

$$
W\left(\vec{k}, \vec{k}^{\prime} \mid \mathbf{c}\right)=\frac{1}{N\langle k\rangle} \sum_{i j} c_{i j} \delta_{\vec{k}, \vec{k}_{i}(\mathbf{c})} \delta_{\vec{k}^{\prime}, \vec{k}_{j}(\mathbf{c})}
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- $W(\vec{k} \mid \mathbf{c}) \equiv \sum_{\vec{k}^{\prime}} W\left(\vec{k}, \vec{k}^{\prime}\right)=p(\vec{k} \mid \mathbf{c}) k^{\text {in }} /\langle k\rangle$
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so focus on:

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\Pi\left(\vec{k}, \vec{k}^{\prime} \mid \mathbf{c}\right)=\frac{W\left(\vec{k}, \vec{k}^{\prime} \mid \mathbf{c}\right)}{W_{1}(\vec{k} \mid \mathbf{c}) W_{2}\left(\overrightarrow{k^{\prime}} \mid \mathbf{c}\right)}
$$

$\Pi\left(\vec{k}, \vec{k}^{\prime} \mid \mathbf{c}\right) \neq 1:$
structural information in degree correlations

## Graph classification

 via increasingly detailed measurements

- proxies for real networks in stat mech process modelling
- complexity: how many networks exist with same features as c?
- hypothesis testing: graphs with controlled features as null models
- quantifying network dissimilarity
analytically in leading order in $N$

Graph classification via increasingly detailed measurements
we are led to study:

## Tailored random graph ensembles


maximum entropy random graph ensembles, with prescribed values for $\langle k\rangle, p(k), \Pi\left(k, k^{\prime}\right), \ldots$

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analytically in leading order in $N$
effective $\mathbf{n r}$ of graphs in ensemble $p(\mathbf{c})$, complexity of tailored random graphs

$$
\mathcal{N}=e^{N\langle k\rangle S}, \quad S=-\frac{1}{N\langle k\rangle} \sum_{\mathbf{c}} p(\mathbf{c}) \log p(\mathbf{c})
$$

- nondirected graphs:

$$
\begin{aligned}
& \quad p(\mathbf{c})=\frac{\prod_{i} \delta_{k_{i}, k_{i}(\mathbf{c})}}{Z} \prod_{i<j}\left[\frac{\langle k\rangle}{N} \frac{W\left(k_{i}, k_{j}\right)}{p\left(k_{i}\right) p\left(k_{j}\right)} \delta_{c_{i j}, 1}+\left(1-\frac{\langle k\rangle}{N} \frac{W\left(k_{i}, k_{j}\right)}{p\left(k_{i}\right) p\left(k_{j}\right)}\right) \delta_{c_{i j}, 0}\right] \\
& \text { - write } \delta_{k_{i}, k_{i}(\mathbf{c})}=(2 \pi)^{-1} \int_{0}^{2 \pi} \mathrm{~d} \omega_{i} \mathrm{e}^{\mathrm{i} \omega_{i}\left[k_{i}-k_{i}(\mathbf{c})\right]} \\
& \text { - factorisation over bonds, sum over graphs } \\
& \text { - write as path integral over } P(k, \omega)=N^{-1} \sum_{i} \delta_{k, k_{i}} \delta\left(\omega-\omega_{i}\right) \\
& \text { - integration via steepest descent } \\
& \text { - solve saddle-point equation analytically }
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$$
\begin{equation*}
S=\frac{1}{2}\left[1+\log \left(\frac{N}{\langle k\rangle}\right)\right]-\left\{\frac{1}{\langle k\rangle} \sum_{k} p(k) \log \left[\frac{1}{\pi(k)}\right]+\frac{1}{2} \sum_{k, k^{\prime}} W\left(k, k^{\prime}\right) \log \left[\frac{W\left(k, k^{\prime}\right)}{W(k) W\left(k^{\prime}\right)}\right]\right\} \tag{N}
\end{equation*}
$$

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- directed graphs:

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$$

with $\vec{k}_{i}(\mathbf{c})=\left(k_{i}^{\text {in }}(\mathbf{c}), k_{i}^{\text {out }}(\mathbf{c})\right)$
similar methods
final result:
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similar methods ...
final result:

$$
\begin{aligned}
& S=+\log \left(\frac{N}{\langle k\rangle}\right) \\
& \quad-\left\{\frac{1}{\langle k\rangle} \sum_{\vec{k}} p(\vec{k}) \log \left[\frac{1}{\pi\left(k^{\text {in }}\right) \pi\left(k^{\text {out }}\right)}\right]+\sum_{\vec{k}, \vec{k}^{\prime}} W\left(\vec{k}, \vec{k}^{\prime}\right) \log \left[\frac{W\left(\vec{k}, \vec{k}^{\prime}\right)}{W(\vec{k}) W\left(\vec{k}^{\prime}\right)}\right]\right\} \\
&+\epsilon_{N}
\end{aligned}
$$

## Information in degree correlations?

plot $\Pi\left(k, k^{\prime}\right)=W\left(k, k^{\prime}\right) / W(k) W\left(k^{\prime}\right)$ for protein interaction networks: a problem ...

structural dissimilarity of graphs $\mathbf{c}_{A}$ and $\mathbf{c}_{B}$, based on Information-theoretic distance between associated ensembles

$$
D_{A B}=\frac{1}{2 N} \sum_{\mathbf{c} \in G}\left\{p\left(\mathbf{c} \mid p_{A}, W_{A}\right) \log \left[\frac{p\left(\mathbf{c} \mid p_{A}, W_{A}\right)}{p\left(\mathbf{c} \mid p_{B}, W_{B}\right)}\right]+p\left(\mathbf{c} \mid p_{B}, W_{B}\right) \log \left[\frac{p\left(\mathbf{c} \mid p_{B}, W_{B}\right)}{p\left(\mathbf{c} \mid p_{A}, W_{A}\right)}\right]\right\}
$$

## same methods as in calculating

Shannon entropy:

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same methods as in calculating
Shannon entropy:

$$
\begin{aligned}
D_{A B}= & \frac{1}{2} \sum_{k} p_{A}(k) \log \left[\frac{p_{A}(k)}{p_{B}(k)}\right]+\frac{1}{2} \sum_{k} p_{B}(k) \log \left[\frac{p_{B}(k)}{p_{A}(k)}\right] \\
& +\frac{1}{4\langle k\rangle_{A}} \sum_{k k^{\prime}} p_{A}(k) p_{A}\left(k^{\prime}\right) k k^{\prime} \Pi_{A}\left(k, k^{\prime}\right) \log \left[\frac{\Pi_{A}\left(k, k^{\prime}\right)}{\Pi_{B}\left(k, k^{\prime}\right)}\right] \\
& +\frac{1}{4\langle k\rangle_{B}} \sum_{k k^{\prime}} p_{B}(k) p_{B}\left(k^{\prime}\right) k k^{\prime} \Pi_{B}\left(k, k^{\prime}\right) \log \left[\frac{\Pi_{B}\left(k, k^{\prime}\right)}{\Pi_{A}\left(k, k^{\prime}\right)}\right] \\
& +\frac{1}{2} \sum_{k} p_{A}(k) k \log \rho_{A B}(k)+\frac{1}{2} \sum_{k} p_{B}(k) k \log \rho_{B A}(k)
\end{aligned}
$$

with

$$
\Pi\left(k, k^{\prime}\right)=W(k, k) / W(k) W\left(k^{\prime}\right), \quad \rho_{A B}(k)=\sum_{k^{\prime}} \Pi_{B}\left(k, k^{\prime}\right) W_{A}\left(k^{\prime}\right) \rho_{A B}^{-1}\left(k^{\prime}\right)
$$

clustering of protein interaction networks with
information-theoretic distance measure


- PINs of same species and measured via same experimental method are statistically similar (in spite of limited overlap)
- PINs measured via same method cluster together, revealing bias introduced by experimental method that overrules species information
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finally: let us


## generate tailored random graphs

from the above families numerically ...

## Generating tailored random graphs numerically

$G[\mathbf{k}]$ : all nondirected graphs $\mathbf{c}$ with degrees $\mathbf{k}$

## how to generate

- random $\mathbf{c} \in G[\mathbf{k}]$, with uniform probability
- random $\mathbf{c} \in G[\mathbf{k}]$, with specified probability $p(\mathbf{c})$ (e.g. tailored graphs)



## available approaches

- matching algorithm (Bender \& Canfield, 1978)
builds one random graph c with specified degrees k
(assign $k_{i}$ 'stubs' to each node $i$, then randomly connect pairs of 'stubs')
- edge switching algorithm (Seidel, 1976; Taylor, 1981)
ergodic Markov process in $G[k]$
$\mathrm{c} \rightarrow \mathrm{c}^{\prime} \rightarrow \mathrm{c}^{\prime \prime} \rightarrow$
- sampling all graphs in $G[\mathbf{k}]$ : in principle easy
- main problem: sampling with correct probabilities
- matching and edge switching: both biased (yet widely used


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## Matching algorithm

- stochastic growth dynamics
- start with graph without any links
- pick at random two nodes whose in- and out degrees have not yet reached required values, and connect these if possible (Bender \& Canfield, 1978)
bond creation as elementary moves:
$c_{i j}=0 \rightarrow c_{i j}=1$

if $k_{i}^{\text {in }}(\mathbf{c})<k_{i}^{\text {in }}$ and $k_{j}^{\text {out }}(\mathbf{c})<k_{j}^{\text {out }}$
origin of sampling bias:
- process can terminate before $k_{i}(\mathrm{c})=k_{i}$ for all $i$ (e.g. if remaining 'stubs' require self-loops)
- requires 'backtracking' which creates correlations between graph realisations


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## Edge switching

- construct arbitrary graph with degrees $\mathbf{k}$
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- are ergodic on $G[\mathbf{k}]$ (Taylor, 1981)
origin of sampling bias:
nr of possible moves
depends on state c!
result:
stationary state of Markov chain
favours high-mobility graphs
dangerous for scale-free graphs


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## Constrained Markovian graph dynamics

need to study graph dynamics more systematically ...

- constraints:
$G[\star] \subseteq G: \quad$ all $\mathbf{c} \in G$ that satisfy constraints *
- stochastic graph dynamics as a Markov chain,
transition probabilities $W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)$

- allowed moves (exclude identity):

क: set of allowed moves $F: G_{F}[*] \rightarrow G[*]$
$G_{F}[\star]$ : those $c \in G[\star]$ on which $F$ can act
all moves are auto-invertible: $(\forall F \in \Phi): F^{2}=\mathbf{I}$
$\Phi$ is ergodic on $G[\star]$

- graph mobility $n(\mathbf{c})$ :



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$$
\forall \mathbf{c} \in G[\star]: \quad p_{t+1}(\mathbf{c})=\sum_{\mathbf{c}^{\prime} \in G[\star]} W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right) p_{t}\left(\mathbf{c}^{\prime}\right)
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need to study graph dynamics more systematically ...

- constraints:
$G[\star] \subseteq G: \quad$ all $\mathbf{c} \in G$ that satisfy constraints $\star$
- stochastic graph dynamics as a Markov chain, transition probabilities $W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)$

$$
\forall \mathbf{c} \in G[\star]: \quad p_{t+1}(\mathbf{c})=\sum_{\mathbf{c}^{\prime} \in G[\star]} W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right) p_{t}\left(\mathbf{c}^{\prime}\right)
$$

- allowed moves (exclude identity):
$\Phi$ : $\quad$ set of allowed moves $F: G_{F}[\star] \rightarrow G[\star]$
$G_{F}[\star]$ : those $\mathbf{c} \in G[\star]$ on which $F$ can act
all moves are auto-invertible: $(\forall F \in \Phi): F^{2}=\mathbf{I}$
$\Phi$ is ergodic on $G[\star]$
- graph mobility $n(\mathbf{c})$ :

$$
n(\mathbf{c})=\sum_{F \in \Phi} I_{F}(\mathbf{c}), \quad I_{F}(\mathbf{c})= \begin{cases}1 & \text { if } \mathbf{c} \in G_{F}[\star] \\ 0 & \text { if } \mathbf{c} \notin G_{F}[\star]\end{cases}
$$

## MCMC objective

 construct transition probs $W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)$, based on moves $F \in \Phi$, such that process converges to $p_{\infty}(\mathbf{c})=Z^{-1} e^{-H(\mathbf{c})}$ on $G[\star]$- structure:

$q(F \mid \mathbf{c})$ : move proposal probability A(c|c'): move acceptance probability
- detailed balance condition:

allowed $F$ equally probable: $q(F \mid \mathbf{c})=I_{F}(\mathbf{c}) / n(\mathbf{c})$


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$$
W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)=\sum_{F \in \Phi} q\left(F \mid \mathbf{c}^{\prime}\right)\left[\delta_{\mathbf{c}, F \mathbf{c}^{\prime}} A\left(F \mathbf{c}^{\prime} \mid \mathbf{c}^{\prime}\right)+\delta_{\mathbf{c}, \mathbf{c}^{\prime}}\left[1-A\left(F \mathbf{c}^{\prime} \mid \mathbf{c}^{\prime}\right)\right]\right]
$$

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$$
\begin{array}{ll}
q(F \mid \mathbf{c}): & \text { move proposal probability } \\
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\end{array}
$$

- detailed balance condition:

$$
(\forall F \in \Phi)(\forall \mathbf{c} \in G[\star]): \quad q(F \mid \mathbf{c}) A(F \mathbf{c} \mid \mathbf{c}) \mathrm{e}^{-H(\mathbf{c})}=q(F \mid F \mathbf{c}) A(\mathbf{c} \mid F \mathbf{c}) \mathrm{e}^{-H(F \mathbf{c})}
$$

allowed $F$ equally probable:
$q(F \mid \mathbf{c})=I_{F}(\mathbf{c}) / n(\mathbf{c})$

$$
(\forall F \in \Phi)\left(\forall \mathbf{c} \in G_{F}[\star]\right): \quad \frac{1}{n(\mathbf{c})} A(F \mathbf{c} \mid \mathbf{c}) \mathrm{e}^{-H(\mathbf{c})}=\frac{1}{n(F \mathbf{c})} A(\mathbf{c} \mid F \mathbf{c}) \mathrm{e}^{-H(F \mathbf{c})}
$$

## canonical Markov chain

ergodic auto-invertible moves $F \in \Phi$, convergence to $p_{\infty}(\mathbf{c})=Z^{-1} e^{-H(\mathbf{c})}$ on $G[\star]$ for acceptance probabilities

$$
A\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)=\frac{n\left(\mathbf{c}^{\prime}\right) \mathrm{e}^{-\frac{1}{2}\left[H(\mathbf{c})-H\left(\mathbf{c}^{\prime}\right)\right]}}{n\left(\mathbf{c}^{\prime}\right) \mathrm{e}^{-\frac{1}{2}\left[H(\mathbf{c})-H\left(\mathbf{c}^{\prime}\right)\right]}+n(\mathbf{c}) \mathrm{e}^{\frac{1}{2}\left[H(\mathbf{c})-H\left(\mathbf{c}^{\prime}\right)\right]}}
$$

naive edge-swapping, $A\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)=$ const,
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$$

## corollary:

naive edge-swapping, $A\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)=$ const, corresponds to $H(\mathbf{c})=-\log n(\mathbf{c})$, so would give

$$
\text { sampling bias : } \quad p_{\infty}(\mathbf{c})=\frac{n(\mathbf{c})}{\sum_{\mathbf{c}^{\prime} \in G[\star]} n\left(\mathbf{c}^{\prime}\right)}
$$

## Master equation representation of the process

- soln of Markov chain: $p_{n}(\mathbf{c}), n=0,1,2, \ldots$
continuous time process, $p_{t}(\mathbf{c}), t \in[0, \infty\rangle$
via random durations of MC steps
$\pi_{m}(t)=(t / \tau)^{m} \mathrm{e}^{-t / \tau} / m!:$
prob that at time $t$ precisely $m$ MC steps have been made

$$
\tau \frac{\mathrm{d}}{\mathrm{~d} t} p_{t}(\mathbf{c})=\sum_{\mathbf{c}^{\prime} \in G[\star]} W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right) p_{t}\left(\mathbf{c}^{\prime}\right)-p_{t}(\mathbf{c})
$$

- work out details, using $\Delta_{F} U(\mathbf{c})=U(F \mathbf{c})-U(\mathbf{c})$

$$
\begin{aligned}
\tau \frac{\mathrm{d}}{\mathrm{~d} t} p_{t}(\mathbf{c}) & =\sum_{F \in \Phi} I_{F}(\mathbf{c})\left\{\frac{w_{F}^{+}(\mathbf{c})}{n(F \mathbf{c})} p_{t}(F \mathbf{c})-\frac{w_{F}^{-}(\mathbf{c})}{n(\mathbf{c})} p_{t}(\mathbf{c})\right\} \\
w_{F}^{ \pm}(\mathbf{c}) & =\frac{1}{2} \pm \frac{1}{2} \tanh \left[\frac{1}{2} \Delta_{F}[H(\mathbf{c})+\log n(\mathbf{c})]\right]
\end{aligned}
$$

- Convergence:

$$
\text { let } \hat{p}(\mathbf{c})=Z^{-1} \mathrm{e}^{-H(\mathbf{c})}, \quad F(t)=\sum_{\mathbf{c} \in G[\star]} p_{t}(\mathbf{c}) \log \left[p_{t}(\mathbf{c}) / \hat{p}(\mathbf{c})\right]
$$

$F(t)$ is Lyapunov function

$$
\forall t \geq 0: \quad F(t) \geq 0, \quad \frac{\mathrm{~d}}{\mathrm{~d} t} F(t) \leq 0
$$

- Proof (standard):
use detailed balance

$\left(e^{x}-e^{y}\right)(x-y) \geq 0$, equality only if $x=y$
- stationarity: ${ }^{\mathrm{d}} \mathrm{F}(\mathrm{t})=0$,
write $p(\mathbf{c})=\chi(\mathbf{c}) \mathrm{e}^{-H(\mathbf{c})}$,

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$$
\left.\left.\begin{array}{rl}
\frac{\mathrm{d}}{\mathrm{~d} t} F(t)=-\frac{1}{2 \tau} \sum_{\mathbf{c}, \mathbf{c}^{\prime} \in G[*]} W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right) \mathrm{e}^{-H\left(\mathbf{c}^{\prime}\right)} & {[ }
\end{array}\left[H(\mathbf{c})+\log p_{t}(\mathbf{c})\right]-\left[H\left(\mathbf{c}^{\prime}\right)+\log p_{t}\left(\mathbf{c}^{\prime}\right)\right]\right] .\right] ~\left(\mathrm{e}^{H(\mathbf{c})+\log p_{t}(\mathbf{c})}-\mathrm{e}^{H\left(\mathbf{c}^{\prime}\right)+\log p_{t}\left(\mathbf{c}^{\prime}\right)}\right] \leq 0 \quad \$
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- stationarity: $\frac{\mathrm{d}}{\mathrm{d} t} F(t)=0$, write $p(\mathbf{c})=\chi(\mathbf{c}) \mathrm{e}^{-H(\mathbf{c})}$,

$$
\begin{aligned}
& \left(\forall \mathbf{c}, \mathbf{c}^{\prime} \in G[\star]\right): \quad W\left(\mathbf{c} \mid \mathbf{c}^{\prime}\right)=0 \text { or } \chi(\mathbf{c})=\chi\left(\mathbf{c}^{\prime}\right) \\
& \text { ergodic } \Rightarrow \chi(\mathbf{c})=\text { const } \Rightarrow p(\mathbf{c})=Z^{-1} \mathrm{e}^{-H(\mathbf{c})}=\hat{p}(\mathbf{c})
\end{aligned}
$$

## Degree-constrained dynamics of nondirected graphs

- constraints: imposed degrees, so graph set is $G[\mathbf{k}]$
ergodic set $\Phi$ of admissible moves:
edge swaps $F: G_{F}[\mathbf{k}] \rightarrow G[\mathbf{k}]$
$Q=\{(i, j, k, \ell) \in\{1$
$\left.N\}^{4} \mid i<j<k<\ell\right\}$, ordered node quadruplets
possible edge swaps to act on $(i, j, k, \ell)$ :

- group into pairs (I,IV), (II,V), and (III,VI)
auto-invertible swaps: $F_{i j k \ell ; \alpha}$, with $i<j<k<\ell$ and $\alpha \in\{1,2,3\}$ $l_{i j k \ell_{i \alpha}}(\mathbf{c})=1$



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$F_{i j k \ell ; \alpha}(\mathbf{c})_{q r}=1-c_{q r} \quad$ for $(q, r) \in \mathcal{S}_{i j k \ell ; \alpha}$
$F_{i j k \ell ; \alpha}(\mathbf{c})_{q r}=c_{q r} \quad$ for $(q, r) \notin \mathcal{S}_{i j k \ell ; \alpha}$
$\mathcal{S}_{i j k \ell ; 1}=\{(i, j),(k, \ell),(i, \ell),(j, k)\}, \quad \mathcal{S}_{i j k \ell ; 2}=\{(i, j),(k, \ell),(i, k),(j, \ell)\}$
$\mathcal{S}_{i j k \ell ; 3}=\{(i, k),(j, \ell),(i, \ell),(j, k)\}$
to implement the Markov chain, need to calculate graph mobility analytically

$$
n(\mathbf{c})=\sum_{i<j<k<\ell}^{N} \sum_{\alpha=1}^{3} I_{j j k ; i \alpha}(\mathbf{c}) \ldots
$$

$$
\begin{aligned}
& \iota_{i j k \ell ; 1}(\mathbf{c})=c_{i j} c_{k \ell}\left(1-c_{i \ell}\right)\left(1-c_{j k}\right)+\left(1-c_{i j}\right)\left(1-c_{k \ell}\right) c_{i \ell} c_{j k} \\
& \iota_{i j k \ell ; 2}(\mathbf{c})=c_{i j} c_{k \ell}\left(1-c_{i k}\right)\left(1-c_{j \ell}\right)+\left(1-c_{i j}\right)\left(1-c_{k \ell}\right) c_{i k} c_{j \ell} \\
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\end{aligned}
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combinatorial problem easily solved:

- computational feasibility:
calculate change $\Delta_{i j k i \alpha} n(c)$ for each executed move $F_{i j k \ell ;}$
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\end{aligned}
$$

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$$
n(\mathbf{c})=\underbrace{\frac{1}{4} N^{2}\langle k\rangle^{2}+\frac{1}{4} N\langle k\rangle-\frac{1}{2} N\left\langle k^{2}\right\rangle}_{\text {invariant }}+\underbrace{\frac{1}{4} \operatorname{Tr}\left(\mathbf{c}^{4}\right)+\frac{1}{2} \operatorname{Tr}\left(\mathbf{c}^{3}\right)-\frac{1}{2} \sum_{i j} k_{i} c_{i j} k_{j}}_{\text {state dependent }}
$$

- state-dependent part can be ignored if $\left\langle k^{2}\right\rangle k_{\max } /\langle k\rangle^{2} \ll N$ (in which case naive edge swapping is harmless)
- computational feasibility:
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$$
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## Example

$N=100$
naive versus correct acceptance probabilities
many possible moves only one move ...
predictions:
$p(\mathbf{c})=$ constant $:$
$\overline{n(\mathbf{c})} / N^{2} \approx 0.0195$
$p(\mathbf{c})=n(\mathbf{c}) / Z$ :
$\overline{n(\mathbf{c})} / N^{2} \approx 0.0242$


## Example


$N=4000$,

$$
\Pi\left(k, k^{\prime}\right)=\frac{\left(k-k^{\prime}\right)^{2}}{\left[\beta_{1}-\beta_{2} k+\beta_{3} k^{2}\right]\left[\beta_{1}-\beta_{2} k^{\prime}+\beta_{3} k^{\prime 2}\right]}
$$

## Degree-constrained dynamics of directed graphs

- constraints: imposed in-out degrees, so graph set is $G\left[\mathbf{k}^{\text {in }}, \mathbf{k}^{\text {out }}\right]$
set $\Phi$ of admissible moves: directed edge swaps $F: G_{F}\left[\mathbf{k}^{\text {in }}, \mathbf{k}^{\text {out }}\right] \rightarrow G\left[\mathbf{k}^{\text {in }}, \mathbf{k}^{\text {out }}\right]$

auto-invertible edge-swaps:
Let $\Lambda=\left\{(i, j) \in N^{2} \mid c_{i j}=1\right\}$


If $I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}=1$ :


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- auto-invertible edge-swaps:


Let $\Lambda=\left\{(i, j) \in N^{2} \mid c_{i j}=1\right\}$

$$
I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}= \begin{cases}1 & \text { if }\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) \in \Lambda \text { and }\left(i_{x}, j_{y}\right),\left(i_{y}, j_{x}\right) \notin \Lambda \\ 0 & \text { otherwise }\end{cases}
$$

If $l_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}=1$ :

$$
\begin{array}{ll}
F_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}(\mathbf{c})_{i j}=1-c_{i j} & \\
F_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}(\mathbf{c})_{i j}=c_{i j} & \\
\text { otherwise }
\end{array}
$$

## difference with nondirected graphs:

edge swaps no longer ergodic (Rao, 1996) (unless self-interactions are allowed)
further move type required
to restore ergodicity:
3-loop reversal


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$$
\begin{gathered}
I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta}=\left\{\begin{array}{l}
1 \quad \text { if }\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right),\left(j_{y}, i_{x}\right) \in \Lambda \text { and } x_{j}=y_{i} \\
\text { and }\left(j_{x}, i_{x}\right),\left(j_{y}, i_{y}\right),\left(i_{x}, j_{y}\right) \notin \Lambda \\
0 \quad \text { otherwise }
\end{array}\right. \\
F_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta(\mathbf{c})_{i j}=1-c_{i j} \quad \text { for }(i, j) \in \mathcal{S}_{i_{x}, j_{x}, j_{y}}}^{F_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta}(\mathbf{c})_{i j}=c_{i j} \quad \text { for }(i, j) \notin \mathcal{S}_{i_{x}, j_{x}, j_{y}}} \\
\mathcal{S}_{a b c}=\{(a, b),(b, c),(c, a),(b, a),(c, b),(a, c)\}
\end{gathered}
$$

to implement the Markov chain, need to calculate graph mobility analytically:

$$
\begin{aligned}
& n(\mathbf{c})=n_{\square}(\mathbf{c})+n_{\triangle}(\mathbf{c}) \\
& \quad=\sum_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) \in \Lambda} I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}+\sum_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) \in \Lambda} I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta} \\
& I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}=c_{i_{x}, j_{x}} c_{i_{y}, j_{y}}\left(1-c_{i_{x}, j_{y}}\right)\left(1-c_{\left.i_{y}, j_{x}\right)}\right) \\
& I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta}=\delta_{x_{j}, y_{i}} c_{i_{x}, j_{x}} c_{i_{y}, j_{y}} c_{j_{y}, i_{x}}\left(1-c_{\left.j_{x}, i_{x}\right)}\right)\left(1-c_{\left.j_{y}, i_{y}\right)\left(1-c_{i_{x}, j_{y}}\right)}\right)
\end{aligned}
$$

## combinatorial problem easily solved:

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$$
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& n(\mathbf{c})=n_{\square}(\mathbf{c})+n_{\triangle}(\mathbf{c}) \\
& \quad=\sum_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) \in \Lambda} I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}+\sum_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) \in \Lambda} I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta} \\
& I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \square}=c_{i_{x}, j_{x}} c_{i_{y}, j_{y}}\left(1-c_{i_{x}, j_{y}}\right)\left(1-c_{\left.i_{y}, j_{x}\right)}\right) \\
& I_{\left(i_{x}, j_{x}\right),\left(i_{y}, j_{y}\right) ; \Delta}=\delta_{x_{j}, y_{i}} c_{i_{x}, j_{x}} c_{i_{y}, j_{y}} c_{j_{y}, i_{x}}\left(1-c_{\left.j_{x}, i_{x}\right)}\right)\left(1-c_{\left.j_{y}, i_{y}\right)\left(1-c_{i_{x}, j_{y}}\right)}\right)
\end{aligned}
$$

combinatorial problem easily solved:

$$
\begin{aligned}
& n_{\square}(\mathbf{c})=\underbrace{\frac{1}{2} N^{2}\langle k\rangle^{2}-\sum_{j} k_{j}^{\text {in }} k_{j}^{\text {out }}}_{\text {invariant }}+\underbrace{\frac{1}{2} \operatorname{Tr}\left(\mathbf{c}^{2}\right)+\frac{1}{2} \operatorname{Tr}\left(\mathbf{c}^{\dagger} \mathbf{c c}^{\dagger} \mathbf{c}\right)+\operatorname{Tr}\left(\mathbf{c}^{2} \mathbf{c}^{\dagger}\right)-\sum_{i j} k_{i}^{\text {in }} c_{i j} k_{j}^{\text {out }}}_{\text {state dependent }} \\
& n_{\triangle}(\mathbf{c})=\underbrace{\frac{1}{3} \operatorname{Tr}\left(\mathbf{c}^{3}\right)-\operatorname{Tr}\left(\hat{\mathbf{c}} \mathbf{c}^{2}\right)+\operatorname{Tr}\left(\hat{\mathbf{c}}^{2} \mathbf{c}\right)-\frac{1}{3} \operatorname{Tr}\left(\hat{\mathbf{c}}^{3}\right)}_{\text {state dependent }} \\
& \text { with: }\left(\mathbf{c}^{\dagger}\right)_{i j}=c_{j i}, \hat{\mathbf{c}}_{i j}=c_{i j} c_{i j}
\end{aligned}
$$

## Example

$$
\begin{aligned}
& \left(k_{1}^{\text {in }}, k_{1}^{\text {out }}\right)=(0, N-2) \\
& i=2 \ldots N-1: \\
& \quad\left(k_{i}^{\text {in }}, k_{i}^{\text {out }}\right)=(1,1) \\
& \left(k_{N}^{\text {in }}, k_{N}^{\text {out }}\right)=(N-2,0)
\end{aligned}
$$

$$
(N-2)(N-3) \text { moves }
$$


$2 N-7$ moves

predicted values versus
equilibrated dynamics for $\langle n(c)\rangle / N^{2}$ :

|  | prediction for <br> $p(c)=$ const | dynamics with <br> $A\left(c \mid c^{\prime}\right)=1$ | dynamics with <br> $A\left(c \mid c^{\prime}\right)=\left[1+\frac{n(c)}{n\left(c^{\prime}\right)}\right]^{-1}$ |
| :--- | :--- | :--- | :--- |
| $N=17:$ | 27.87 | 33.59 | 27.87 |
| $N=27:$ | 47.92 | 58.32 | 47.95 |

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## Summary

- standard 'matching' end 'edge swapping' algorithms, for generating graphs $\mathbf{c}$ with prescribed degrees, are both biased
- need exact method for generating random graphs $\mathbf{c}$ with prescribed degrees and prescribed sampling probabilities $p(\mathbf{c})$
- exact degree constrained Markovian graph dynamics can be defined, guaranteed to evolve to any prescribed measure $p(\mathbf{c})$
- process requires nontrivial state acceptance probabilities, that involve the mobilities $n(\mathbf{c})$ of states
- nondirected graph: edge swaps only directed graphs: edge swaps and 3-cycle reversals
- mobilities can be calculated exactly
- theory worked out, implemented and tested for nondirected and directed graphs


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## Current and future work

Development of theory for tailored graph ensembles characterised by statistics of loops ...
(in addition to degrees and degree correlations)


- loops versus closed paths (see talk by Clara Gracio)


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Development of theory for tailored graph ensembles characterised by statistics of loops ...
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- calculate Shannon entropies
- dynamics (constrained by degrees and loops)
- graph ensembles defined by eigenvalue spectrum

protein interaction networks
- loops versus closed paths (see talk by Clara Gracio)


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